

Menu availability for each user level

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Menu tree	Operation mode (*1)			User level (*2)			Version (*3)
	Auto	Manual	Teach check	Operator	Programmer	Mentener	
F1 Program	●	●	●	●	●	●	
F1 New	-	●	-	-	●	●	
F5 Edit	-	●	-	-	●	●	
F2 Delete	-	●	-	-	●	●	
F3 Copy	-	●	-	-	●	●	
F4 Paste	-	●	-	-	●	●	
F5 Edit	-	●	-	-	●	●	
F6 Aux	-	●	-	●	●	●	
F1 Program settings	-	●	-	△	●	●	
F5 Program parameters	-	●	-	△	●	●	
F7 StartSupervisory task	-	●	-	●	●	●	
F8 StopSupervisory task	-	●	-	●	●	●	
F10 Delete all static variables	-	●	-	-	●	●	
F11 Delete all programs	-	●	-	-	●	●	
F9 EncryptDecrypt	-	●	-	-	●	●	
F10 FileLock/Unlock	-	●	-	-	●	●	
F11 Rename	-	●	-	-	●	●	
F12 CheckSyntax	-	●	-	-	●	●	
F1 Halt	●	-	●	●	●	●	
F2 StepStop	●	-	●	●	●	●	
F3 CycleStop	●	-	-	●	●	●	
F4 Start	●	-	-	●	●	●	
F4 CycleStart	-	-	●	●	●	●	
F6 StepStart	●	-	●	●	●	●	
F7 Reset	●	-	●	●	●	●	
F9 Priority	●	-	●	-	●	●	
F10 ContinueStart	●	-	-	●	●	●	
F11 Display	●	-	●	●	●	●	
F1 CreateNew	-	●	-	-	●	●	
F2 Cut	-	●	-	-	●	●	
F3 Copy	-	●	-	-	●	●	
F4 Paste	-	●	-	-	●	●	
F5 Edit	-	●	-	-	●	●	
F6 Save &&CheckSyntax	-	●	-	-	●	●	
F7 Comment	-	●	-	-	●	●	
F8 Uncomment	-	●	-	-	●	●	
F9 Format	-	●	-	-	●	●	
F1 Halt	●	-	●	●	●	●	
F2 StepStop	●	-	●	●	●	●	
F3 CycleStop	●	-	-	●	●	●	
F4 Start	●	-	-	●	●	●	
F4 CycleStart	-	-	●	●	●	●	
F6 StepStart	●	-	●	●	●	●	
F7 Reset	●	-	●	●	●	●	
F9 Priority	●	-	●	-	●	●	
F10 ContinueStart	●	-	-	●	●	●	
F2 Arm	●	●	●	●	●	●	
F1 PositionDisplayStyle	●	●	●	●	●	●	
F2 Force Control	●	●	●	●	●	●	
F1 SwitchDisplay	●	●	●	●	●	●	
F2 Force Control Log	●	●	●	●	●	●	
F1 ClearLog	●	●	●	●	●	●	
F2 StartLog	●	●	●	●	●	●	
F3 StopLog	●	●	●	●	●	●	
F4 SaveLog	●	●	●	●	●	●	
F5 Refresh	●	●	●	●	●	●	
F6 Setting	●	●	●	△	●	●	
F7 Switch Y-Value display direction	●	●	●	●	●	●	
F8 Change axis display range	●	●	●	●	●	●	
F6 Sensor	●	●	●	●	●	●	
F1 Sensor Setting	●	●	●	●	●	●	
F2 IP Address Setting	●	●	●	●	●	●	
F3 Connect Sensor	●	●	●	●	●	●	

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	Auto	Manual	Teach check	Operator	Programmer	Mentener	
F7 Sensor Calibration	●	●	●	●	●	●	
F6 Setting	●	●	●	△	●	●	
F12 Detail setting	●	●	●	△	●	●	
F3 Servo State	●	●	●	●	●	●	
F4 Variable	●	●	●	●	●	●	
F6 Aux	●	●	●	●	●	●	
F1 Config	●	●	●	△	●	●	
F2 Collision/Interference	●	●	●	●	●	●	
F1 Collision Detection	●	●	●	△	●	●	
F3 Tool	●	●	●	△	●	●	
F1 Prev	●	●	●	●	●	●	
F2 Next	●	●	●	●	●	●	
F3 Jump To	●	●	●	●	●	●	
F4 EasyEdit	●	●	●	-	●	●	
F1 Prev	●	●	●	-	●	●	
F2 Next	●	●	●	-	●	●	
F3 Jump To	●	●	●	-	●	●	
F4 PntCount	●	●	●	-	●	●	
F5 Edit	●	●	●	-	●	●	
F6 Get Position	●	●	●	-	●	●	
F5 Edit	●	●	●	-	●	●	
F4 Work	●	●	●	△	●	●	
F1 Prev	●	●	●	●	●	●	
F2 Next	●	●	●	●	●	●	
F3 Jump To	●	●	●	●	●	●	
F4 EasyEdit	●	●	●	-	●	●	
F1 Prev	●	●	●	-	●	●	
F2 Next	●	●	●	-	●	●	
F3 Jump To	●	●	●	-	●	●	
F5 Edit	●	●	●	-	●	●	
F6 Get Position	●	●	●	-	●	●	
F5 Edit	●	●	●	-	●	●	
F5 Area	●	●	●	△	●	●	
F1 Prev	●	●	●	●	●	●	
F2 Next	●	●	●	●	●	●	
F3 Jump To	●	●	●	●	●	●	
F4 EasyEdit	●	●	●	-	●	●	
F1 Prev	●	●	●	-	●	●	
F2 Next	●	●	●	-	●	●	
F3 Jump To	●	●	●	-	●	●	
F5 Edit	●	●	●	-	●	●	
F6 Get Position	●	●	●	-	●	●	
F5 Edit	●	●	●	-	●	●	
F7 Detail	●	●	●	△	●	●	
F1 Prev	●	●	●	●	●	●	
F2 Next	●	●	●	●	●	●	
F3 Jump To	●	●	●	●	●	●	
F5 Edit	●	●	●	-	●	●	
F6 PathPoint	●	●	●	△	●	●	
F1 Prev	●	●	●	●	●	●	
F2 Next	●	●	●	●	●	●	
F3 Jump To	●	●	●	●	●	●	
F4 Move To	●	●	●	●	●	●	
F5 Edit	●	●	●	-	●	●	
F6 Get Position	●	●	●	-	●	●	
F8 Copy	●	●	●	●	●	●	
F9 Paste	●	●	●	-	●	●	
F11 Robot	●	●	●	●	●	●	
F7 Display Settings	●	●	●	●	●	●	
F8 Direct Teach	●	●	●	-	●	●	
F9 Z Balance	●	●	●	-	●	●	
F10 Base	●	●	●	△	●	●	
F4 EasyEdit	●	●	●	●	●	●	

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	Auto	Manual	Teach check	Operator	Programmer	Mentener	
F1 Prev	●	●	●	●	●	●	
F2 Next	●	●	●	●	●	●	
F3 Jump To	●	●	●	●	●	●	
F4 Edit	●	●	●	-	●	●	
F5 Get Position	●	●	●	-	●	●	
F5 Change	●	●	●	-	●	●	
F11 Exclusive Control	●	●	●	●	●	●	
F1 Exclusive Area	●	●	●	●	●	●	
F1 Prev	●	●	●	●	●	●	
F2 Next	●	●	●	●	●	●	
F3 Jump To	●	●	●	●	●	●	
F5 Edit	●	●	●	-	●	●	
F2 Exclusive Communication	●	●	●	●	●	●	
F1 Prev	●	●	●	●	●	●	
F2 Next	●	●	●	●	●	●	
F3 Jump To	●	●	●	●	●	●	
F5 Edit	●	●	●	-	●	●	
F12 Maintenance	●	●	●	●	●	●	
F1 Brake	●	●	●	●	●	●	
F4 Release all joints	●	●	●	●	●	●	
F6 Lock All	●	●	●	●	●	●	
F2 Encoder	●	●	●	●	●	●	
F1 Encoder Info	●	●	●	●	●	●	
F7 Reset encoder	●	●	●	-	-	●	
F4 CancelAll	●	●	●	-	-	●	
F6 SelectAll	●	●	●	-	-	●	
F8 Encoder ID	●	●	●	-	-	●	
F9 Encoder reference	●	●	●	-	-	●	
F6 Clear	●	●	●	-	-	●	
F3 Driver Unit	●	●	●	●	●	●	
F7 CALSET	●	●	●	-	-	●	
F1 CALSET	●	●	●	-	-	●	
F4 CancelAll	●	●	●	-	-	●	
F6 SelectAll	●	●	●	-	-	●	
F2 Recover CALSET data	●	●	●	-	-	●	
F4 CancelAll	●	●	●	-	-	●	
F6 SelectAll	●	●	●	-	-	●	
F3 Input Number	●	●	●	-	-	●	
F5 Edit	●	●	●	-	-	●	
F8 Motion Space	●	●	●	△	●	●	
F10 JointSettings	●	●	●	-	●	●	
F1 ArmGroup	●	●	●	-	●	●	
F1 Prev	●	●	●	-	●	●	
F2 Next	●	●	●	-	●	●	
F3 Jump To	●	●	●	-	●	●	
F5 Edit	●	●	●	-	●	●	
F2 ArmSetting	●	●	●	-	-	●	
F1 Prev	●	●	●	-	-	●	
F2 Next	●	●	●	-	-	●	
F3 Jump To	●	●	●	-	-	●	
F5 Change	●	●	●	-	-	●	
F3 LinkInfo	●	●	●	-	●	●	
F1 Prev	●	●	●	-	●	●	
F2 Next	●	●	●	-	●	●	
F3 Jump To	●	●	●	-	●	●	
F5 Edit	●	●	●	-	●	●	
F4 PathParameter	●	●	●	-	-	●	
F1 Prev	●	●	●	-	-	●	
F2 Next	●	●	●	-	-	●	
F3 Jump To	●	●	●	-	-	●	
F5 Change	●	●	●	-	-	●	
F5 ServoParameter	●	●	●	-	-	●	
F1 Prev	●	●	●	-	-	●	

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	Auto	Manual	Teach check	Operator	Programmer	Mentener	
F2 Next	●	●	●	-	-	●	
F3 Jump To	●	●	●	-	-	●	
F5 Change	●	●	●	-	-	●	
F6 MotorSetting	●	●	●	-	-	●	
F1 Prev	●	●	●	-	-	●	
F2 Next	●	●	●	-	-	●	
F3 Jump To	●	●	●	-	-	●	
F5 Change	●	●	●	-	-	●	
F7 Auto GainTuning	●	●	●	-	-	●	
F4 Execute	●	●	●	-	-	●	
F8 EN/DisableArm	●	●	●	-	-	●	
F12 Robot Axis Range	●	●	●	-	-	●	
F12 Service	●	●	●	-	-	●	
F1 Acceleration Limit	●	●	●	-	-	●	
F3 Variable	●	●	●	●	●	●	
F1 Prev	●	●	●	●	●	●	
F2 Next	●	●	●	●	●	●	
F3 Jump To	●	●	●	●	●	●	
F4 MoveTo	●	●	●	●	●	●	
F5 Edit	●	●	●	-	●	●	
F6 Get Position	●	●	●	-	●	●	
F8 Copy	●	●	●	●	●	●	
F9 Paste	●	●	●	-	●	●	
F10 SwitchDisplay	●	●	●	●	●	●	
F11 Robot	●	●	●	●	●	●	
F12 Aux	●	●	●	●	●	●	
F1 Number of Variables	●	●	●	△	●	●	
F5 Edit	●	●	●	-	●	●	
F4 I/O	●	●	●	●	●	●	
F1 Prev	●	●	●	●	●	●	
F2 Next	●	●	●	●	●	●	
F3 Jump To	●	●	●	●	●	●	
F4 DummySmart	●	●	●	●	●	●	
F5 ON/OFF	●	●	●	●	●	●	
F5 Edit	●	●	●	●	●	●	ver1.4
F6 Aux	●	●	●	●	●	●	
F1 I/O Information	●	●	●	●	●	●	
F2 I/O Lock	●	●	●	●	●	●	
F4 Field Bus parameter	●	●	●	△	●	●	
F5 I/O Parameters	●	●	●	△	●	●	
F5 Panel	●	●	●	●	●	●	
F6 Setting	●	●	●	●	●	●	
F1 Login	●	●	●	●	●	●	
F2 System Info	●	●	●	●	●	●	
F3 Pendant and Panel	●	●	●	●	●	●	
F1 Language	●	●	●	●	●	●	
F2 Pendant Setting	●	●	●	△	●	●	
F3 Panel Settings	●	●	●	△	●	●	
F4 Disconnect Pendant	●	●	●	●	●	●	
F7 DSWinterlock	●	●	●	●	●	●	
F4 Operation and ErrorLog	●	●	●	●	●	●	
F5 Comunication and Token	●	●	●	●	●	●	
F1 Executable Token	●	●	●	-	●	●	
F5 Edit	●	●	●	-	●	●	
F2 Network and Permission	●	●	●	△	●	●	
F5 Edit	●	●	●	-	●	●	
F3 Data Comunication	●	●	●	●	●	●	
F5 Edit	●	●	●	-	●	●	
F6 Set COM Port Number	●	●	●	△	●	●	
F4 OPC-UAServer	●	●	●	△	●	●	
F1 Start	●	●	●	-	●	●	
F2 Stop	●	●	●	-	●	●	
F3 Rebuild	●	●	●	-	●	●	

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	Auto	Manual	Teach check	Operator	Programmer	Mentener	
F4 Save	●	●	●	-	●	●	Ver1.7
F7 Ping	●	●	●	●	●	●	
F6 Data Read and Write	●	●	●	-	●	●	
F1 Project Read and Write	●	●	●	-	●	●	
F1 Prev	●	●	●	-	●	●	
F2 Next	●	●	●	-	●	●	
F3 Jump To	●	●	●	-	●	●	
F7 Date and Maintenance	●	●	●	●	●	●	
F1 Date and Maintenance	●	●	●	△	●	●	
F2 Controller Battery	●	●	●	△	●	●	
F3 Encoder Battery	●	●	●	△	●	●	
F8 Option	●	●	●	●	●	●	
F1 Extension	●	●	●	●	●	●	
F1 Prev	●	●	●	●	●	●	
F2 Next	●	●	●	●	●	●	
F3 Jump To	●	●	●	●	●	●	
F4 Remove	●	●	●	-	●	●	
F5 Add	●	●	●	-	●	●	
F7 Change order	●	●	●	●	●	●	
F2 Program-Priority mode	●	●	●	●	●	●	
F9 Cooperation	●	●	●	-	-	●	
F8 Vision	●	●	●	●	●	●	1.5.x
F1 Vision Calibration	●	●	●	●	●	●	1.5.x
F1 Prev	●	●	●	●	●	●	1.5.x
F2 Next	●	●	●	●	●	●	1.5.x
F3 Jump To	●	●	●	●	●	●	1.5.x
F4 Get variable	●	●	●	-	●	●	1.5.x
F5 Edit	●	●	●	-	●	●	1.5.x
F6 Get position	●	●	●	-	●	●	1.5.x
F10 Save CalData	●	●	●	-	●	●	1.6.x
F11 Execute Calibration	●	●	●	-	●	●	1.5.x
F7 Build-in Vision	●	●	●	●	●	●	1.5.x
F1 Change ID	●	●	●	●	●	●	1.5.x
F2 Save Image	●	●	●	●	●	●	
F5 Trigger/Refresh Image	●	●	●	●	●	●	1.6.x
F6 Connect/Disconnect	●	●	●	●	●	●	1.6.x
F9 ServoHand	●	●	●	●	●	●	
F1 Servo Hand No.	●	●	●	●	●	●	
F3 Jump To	●	●	●	●	●	●	
F4 Move To	●	●	●	-	●	●	
F5 Edit	●	●	●	-	●	●	
F6 Read Pos	●	●	●	-	●	●	
F12 Aux	●	●	●	●	●	●	
F1 Initial settings	●	●	●	●	●	●	
F1 Servo Hand No.	●	●	●	●	●	●	
F2 Parameter	●	●	●	△	●	●	
F3 Spacial Parameter	●	●	●	-	-	●	
F10 Tracking	●	●	●	-	●	●	
F1 Start the trigger detection	●	●	●	-	●	●	
F2 Stop the trigger detection	●	●	●	-	●	●	
F4 CAL the Slave(Run mode)	●	●	●	-	●	●	
F5 Master/Slave	●	●	●	-	●	●	
F12 Detail	●	●	●	-	-	●	
F11 MessageLog	●	●	●	●	●	●	
F1 Prev	●	●	●	●	●	●	
F2 Next	●	●	●	●	●	●	
F3 Jump To	●	●	●	●	●	●	
F4 Clear	●	●	●	●	●	●	
F5 Copy	●	●	●	●	●	●	