

Output Data (CC-Link remote device → Master)

Remote Output (RY)

Signal name	I/O port No.			Note
	2 stations occupied 64 points	3 stations occupied 96 points	4 stations occupied 128 points	
(-)	768	768	768	Not available
Robot running	769	769	769	
Robot error	770	770	770	
Servo ON	771	771	771	
Robot initialization completed	772	772	772	
Auto mode	773	773	773	
External mode	774	774	774	
Battery warning	775	775	775	
Robot warning	776	776	776	
Continued start permitted	777	777	777	
SS mode output	778	778	778	
(Reserved)	779	779	779	Not available
(Reserved)	780	780	780	Not available
(Reserved)	781	781	781	Not available
Command processing completed	782	782	782	
Status area odd parity	783	783	783	
Bit 0 in status area	784	784	784	
Bit 1 in status area	785	785	785	
Bit 2 in status area	786	786	786	
Bit 3 in status area	787	787	787	
Bit 4 in status area	788	788	788	
Bit 5 in status area	789	789	789	
Bit 6 in status area	790	790	790	
Bit 7 in status area	791	791	791	
Bit 8 in status area	792	792	792	
Bit 9 in status area	793	793	793	
Bit 10 in status area	794	794	794	
Bit 11 in status area	795	795	795	
Bit 12 in status area	796	796	796	
Bit 13 in status area	797	797	797	
Bit 14 in status area	798	798	798	
Bit 15 in status area	799	799	799	
User output	800	800	800	
	: 815	: 847	: 879	
(System output)	816	848	880	
	: 825	: 857	: 889	Not available
Error status flag	826	858	890	Synchronize with a robot error (I/O port No.770) or a robot warning (I/O port No.776).
Remote station ready	827	859	891	Synchronize with the robot initialized (I/O port No.772).
(System output)	828	860	892	
	: 831	: 863	: 895	Not available

Remote Register Output (RWw)

Signal name	I/O port No.		
	2 stations occupied 8 words	3 stations occupied 12 words	4 stations occupied 16 words
User output	4608 - 4623	4608 - 4623	4608 - 4623
	4624 - 4639	4624 - 4639	4624 - 4639
	4640 - 4655	4640 - 4655	4640 - 4655
	4656 - 4671	:	:
	4672 - 4687	:	:
	4688 - 4703	4752 - 4767	4816 - 4831
	4704 - 4719	4768 - 4783	4832 - 4847
	4720 - 4735	4784 - 4799	4848 - 4863