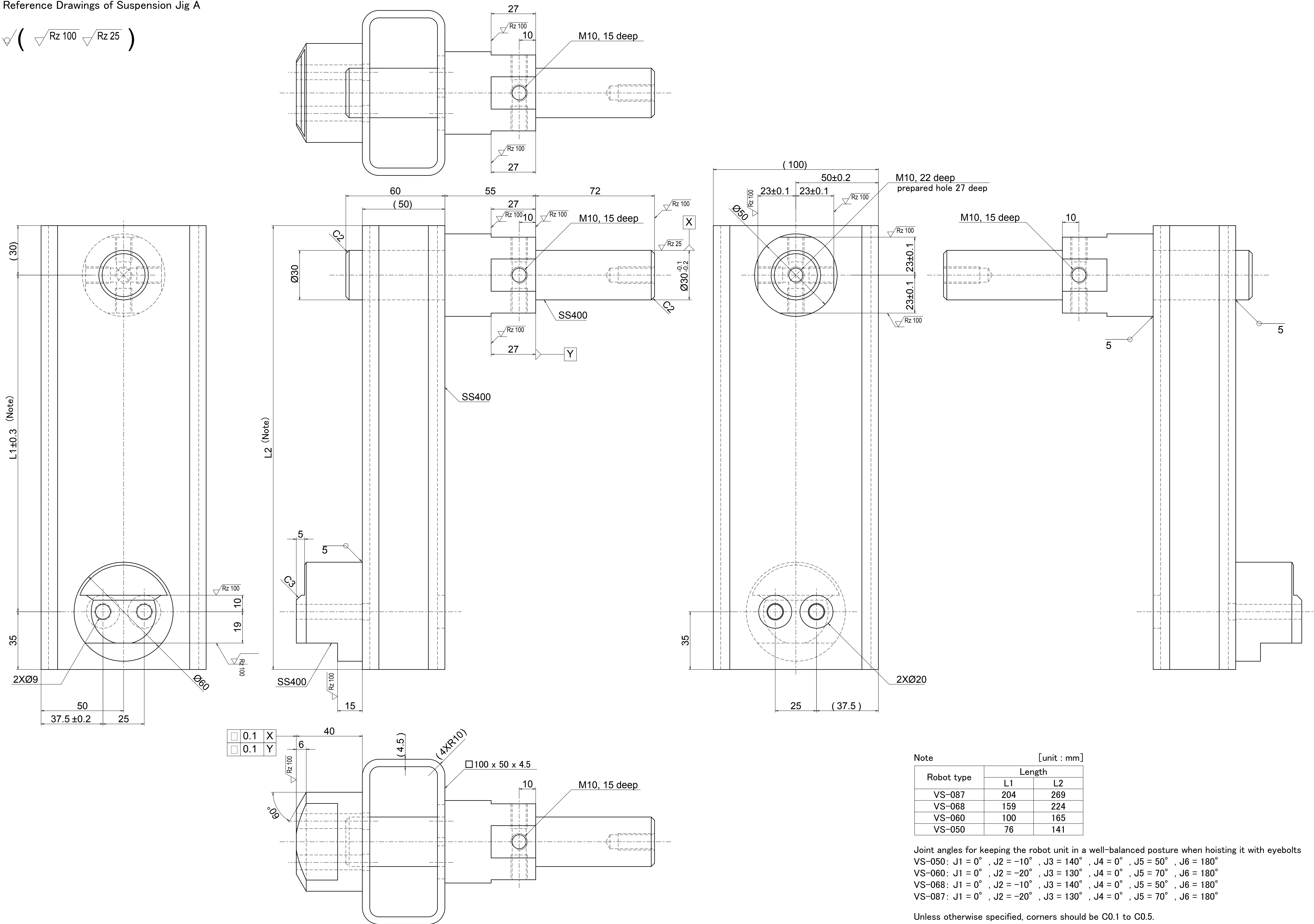


Reference Drawings of Suspension Jig A

▽ (√Rz 100 √Rz 25)



Note [unit : mm]

Robot type	Length	
	L1	L2
VS-087	204	269
VS-068	159	224
VS-060	100	165
VS-050	76	141

Joint angles for keeping the robot unit in a well-balanced posture when hoisting it with eyebolts
 VS-050: J1 = 0° , J2 = -10° , J3 = 140° , J4 = 0° , J5 = 50° , J6 = 180°
 VS-060: J1 = 0° , J2 = -20° , J3 = 130° , J4 = 0° , J5 = 70° , J6 = 180°
 VS-068: J1 = 0° , J2 = -10° , J3 = 140° , J4 = 0° , J5 = 50° , J6 = 180°
 VS-087: J1 = 0° , J2 = -20° , J3 = 130° , J4 = 0° , J5 = 70° , J6 = 180°

Unless otherwise specified, corners should be C0.1 to C0.5.