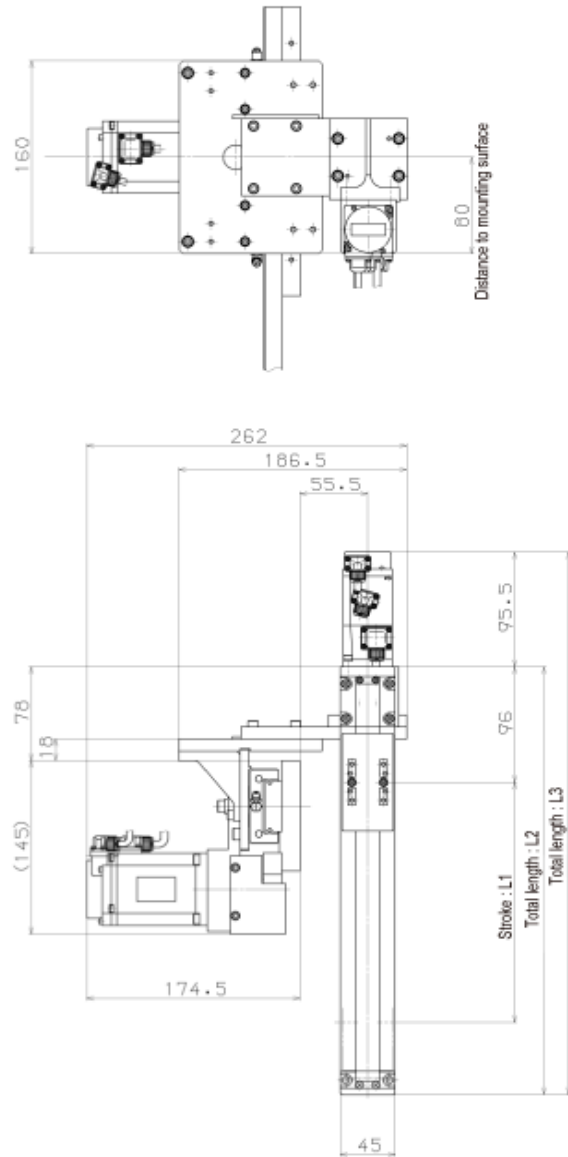
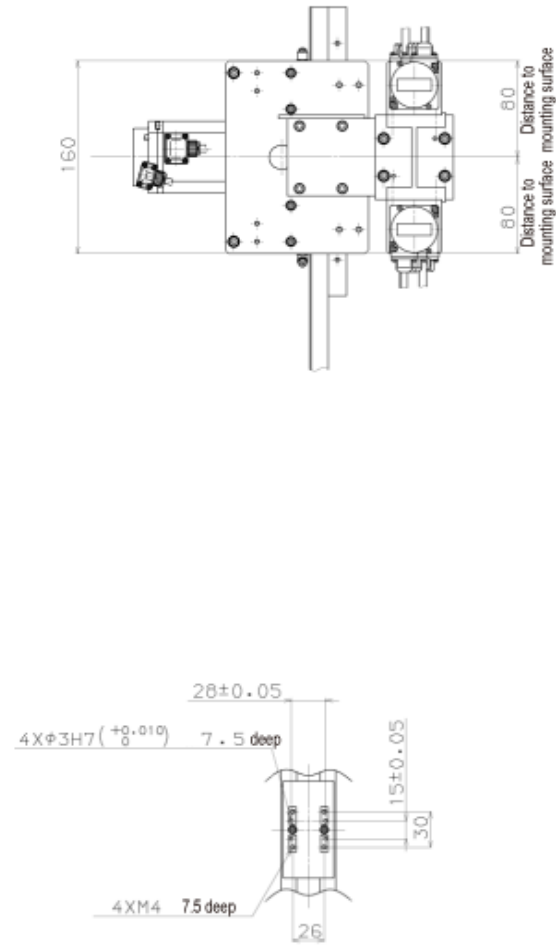


■ Outer Dimensions and Work Space of the Robot Unit

LZNN



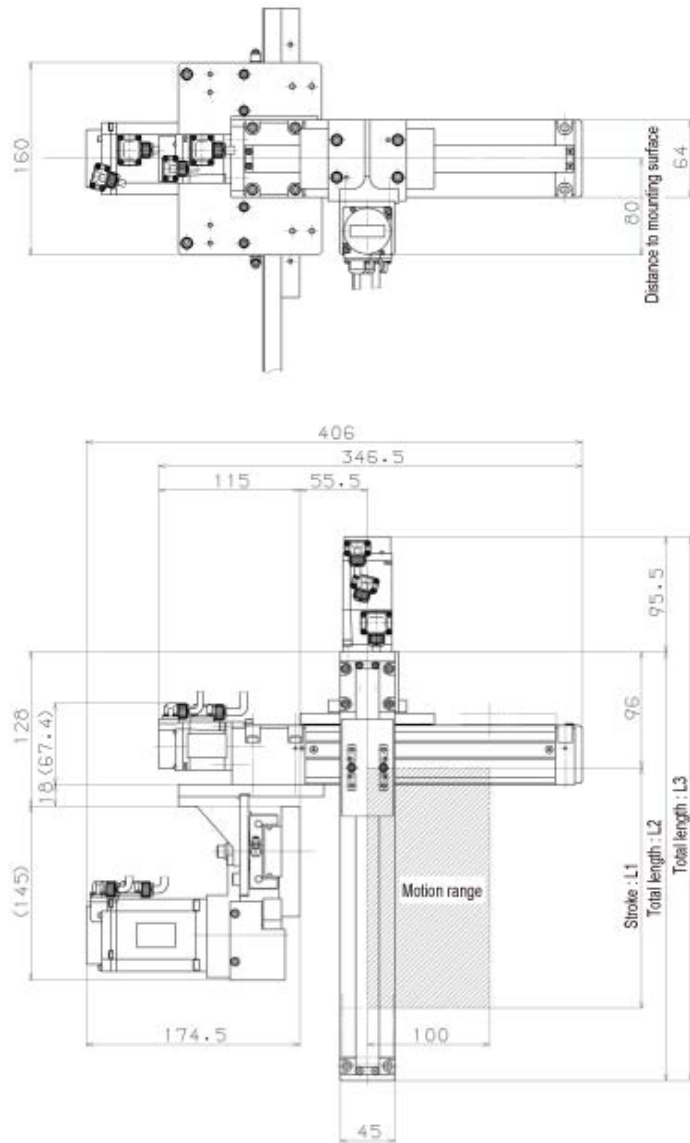
LZZN



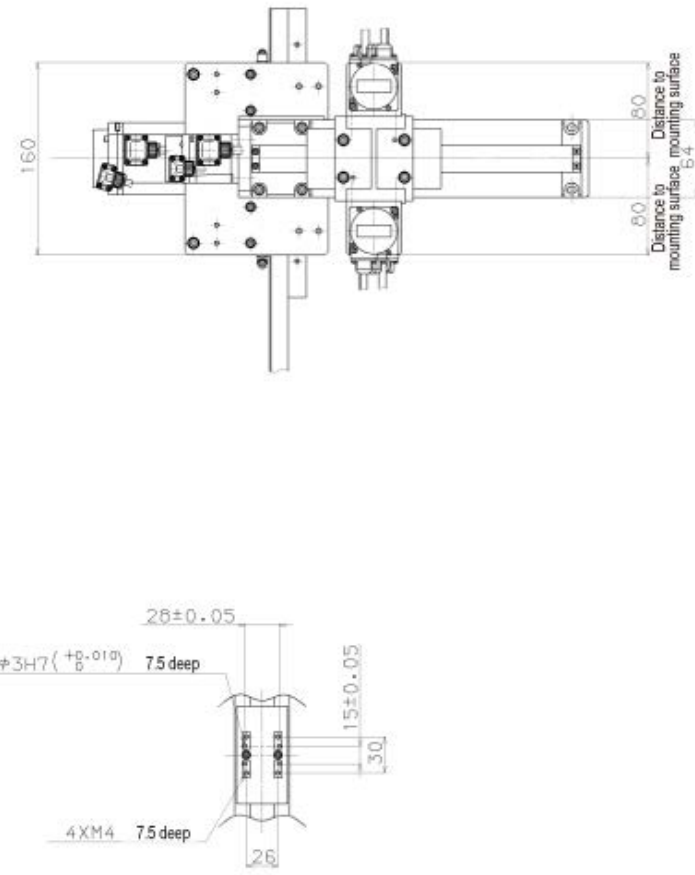
Z axis	Model stroke Unit: 10 mm	010	020
L1 (=Motion stroke)		100	200
L2 (=Total length)		256	356
L3 (=Total length with motor)		351.5	451.5

■ Outer Dimensions and Work Space of the Robot Unit

LYZN



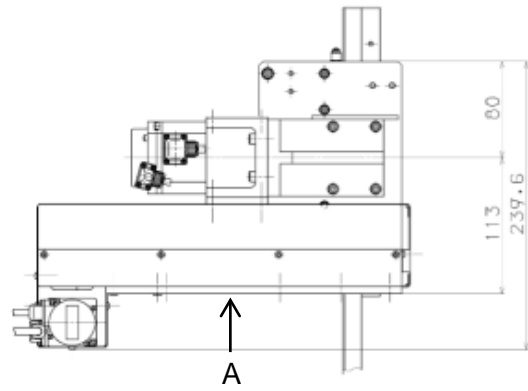
LYZZ



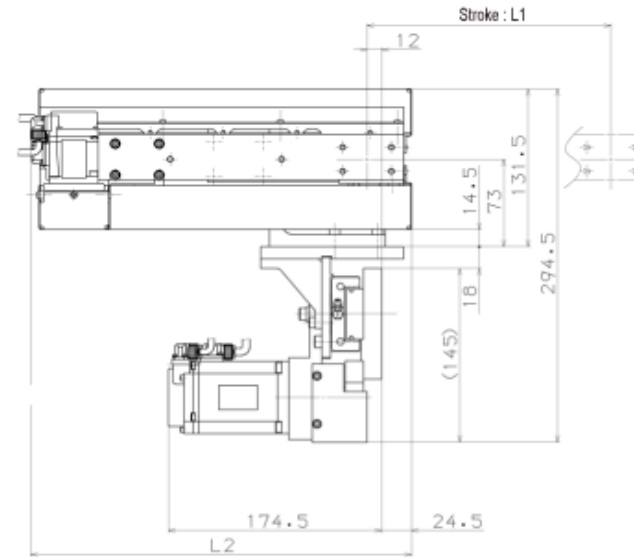
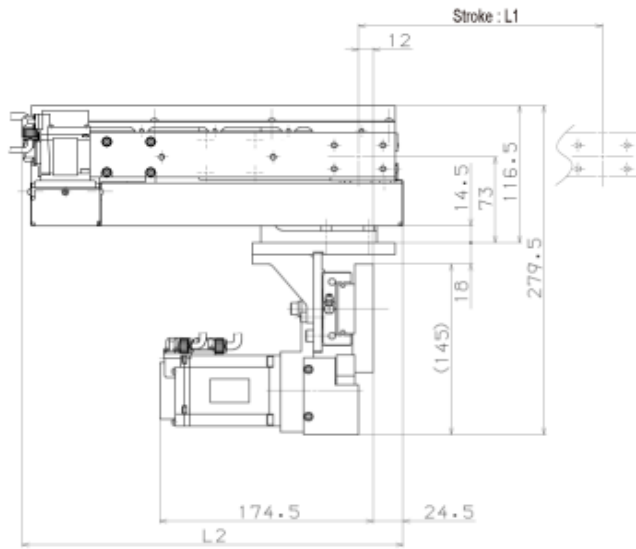
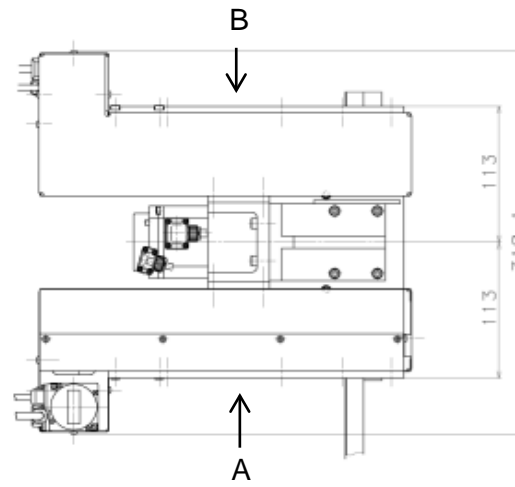
Z axis	Model stroke Unit: 10 mm	010	020
L1 (=Motion stroke)		100	200
L2 (=Total length)		256	356
L3 (=Total length with motor)		351.5	451.5

■ Outer Dimensions and Work Space of the Robot Unit

LSNN



LSSN

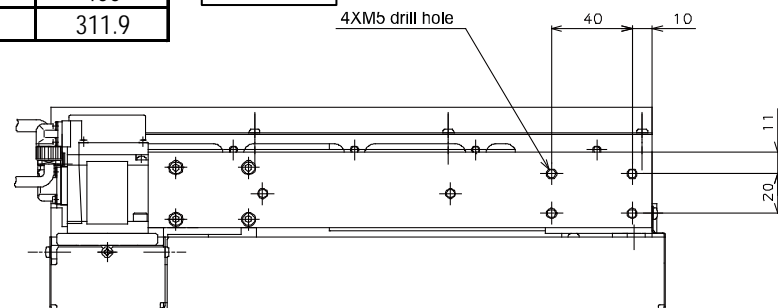


S axis

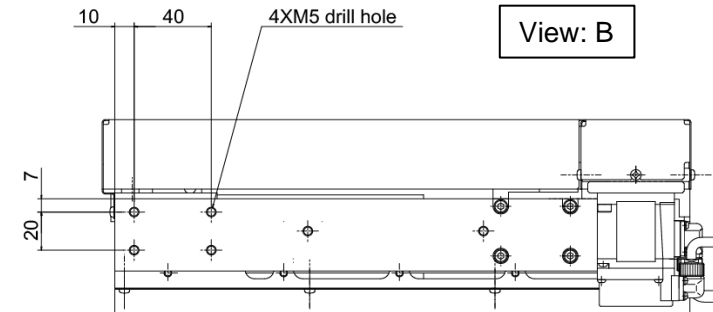
Model stroke Unit: 10 mm	030	040
L1 (=Motion stroke)	300	400
L2 (=Stretch axis length)	261.9	311.9

Installation dimension diagram at the tip of the S-axis

View: A



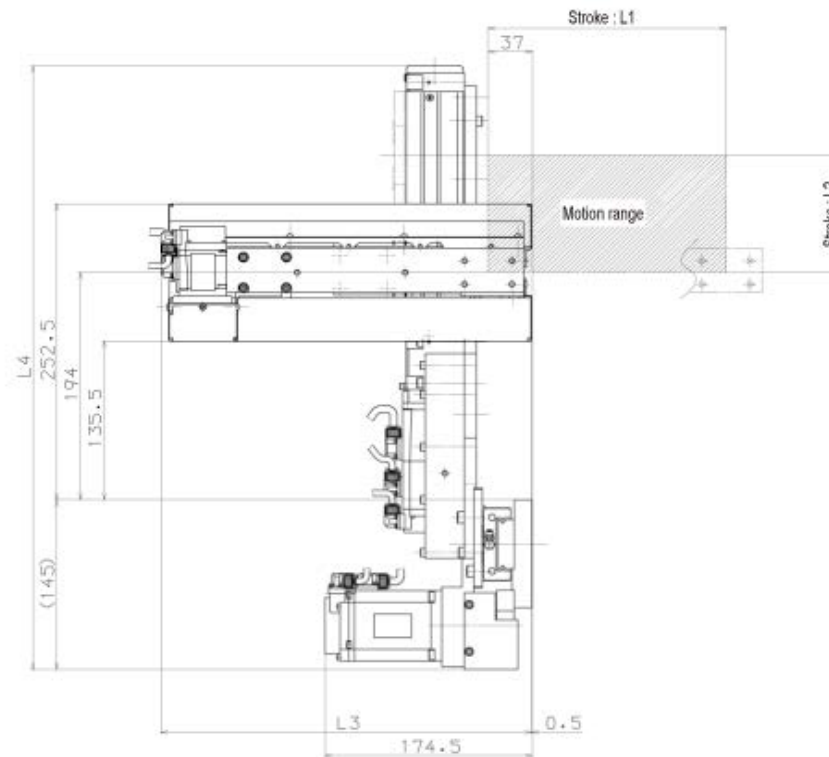
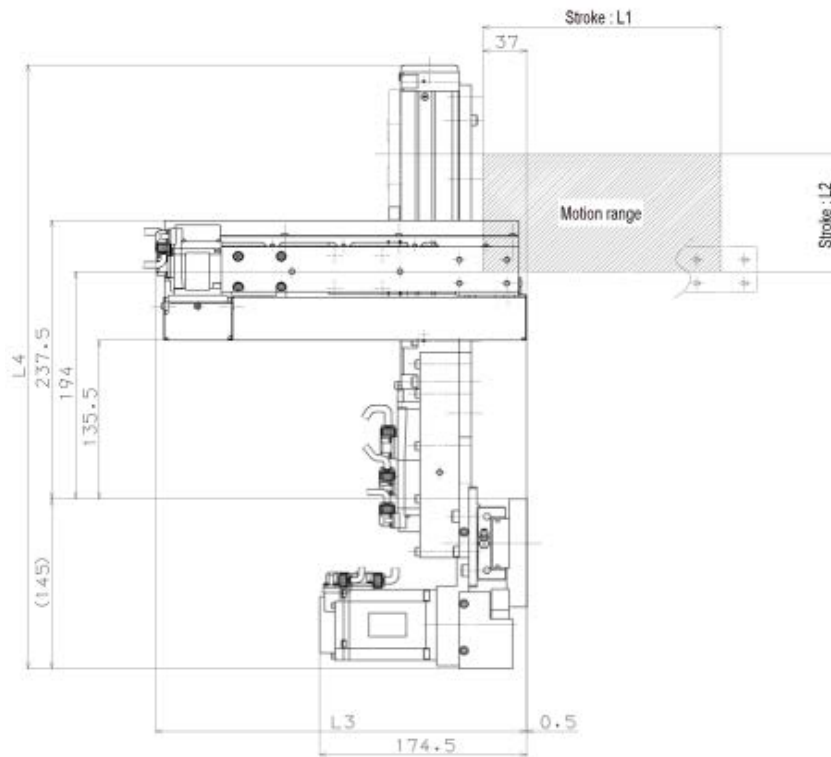
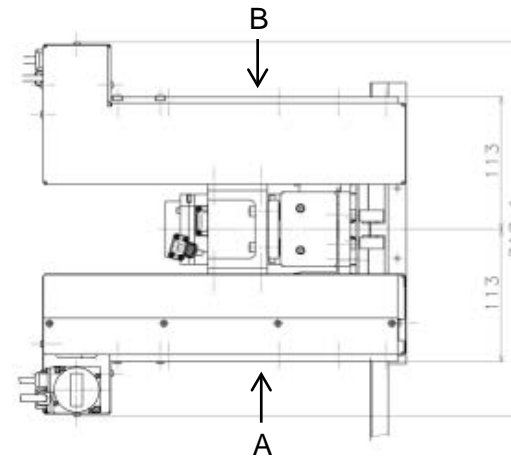
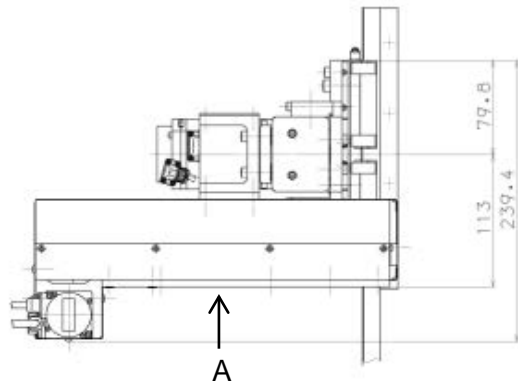
View: B



■ Outer Dimensions and Work Space of the Robot Unit

LZSN

LZSS



S axis	Model stroke Unit: 10 mm	030	040
	L1 (=Motion stroke)	300	400
	L3 (=Stretch axis length)	261.9	311.9

Z axis	Model stroke Unit: 10 mm	010	020
	L2 (=Motion stroke)	100	200
	L3 (=Total length)	526	626

Installation dimension diagram at the tip of the S-axis

