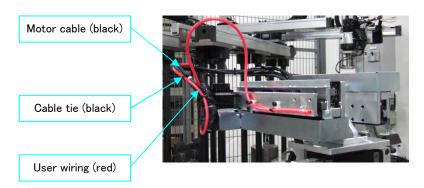
## LSNN, LSSN wiring and piping example

This shows the recommended wiring and piping examples for a system which attaches an end effecter (such as a hand) to the end of the motion range of the S-axis.

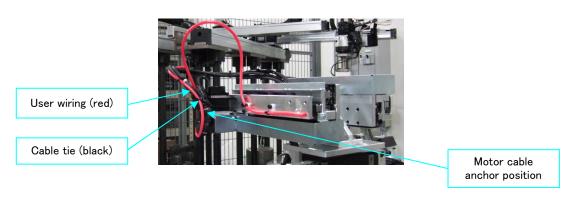
### Step1

Lay user wirings corresponding to the number of wire or pipe diameter along the motor cable, then band it with the cable tie.



#### Step2

Tighten the user wiring to the motor cable anchor position of the S-axis with the cable tie.



#### Step3

Lay the user wiring to an upward direction and slack so as to provide extra length even if the S-axis reaches to the front end position.

Hand plate has screw holes to fix user wirings

Bolt user wirings to screw holes with cable tie and tie holder

Recommended parts
Tie holder
Bolt for screw holes
M5×10

Bolt (black) and tie holder (white)

Note: Lay the cable to an upward direction (yellow arrow)

Hand plate

Cable tie (black)

# Step4

Make sure that the user wirings do not have too much tension at the front end of the S-axis.

User wiring (red)

Note : Check that if the wire has too much tension

